



Class Agenda

- Introduction
- System sizing process
- Basics
- Final note

UAH**CD&H**

- Two functions
 - Receives, validates, decodes, and distributes commands to other spacecraft systems
 - Gathers, processes, and formats spacecraft housekeeping and mission data for downlink or use by an onboard computer
- Size is directly proportional to spacecraft complexity
 - More systems a spacecraft has, the more monitoring and configuration capability required
- Ideal CD&H system is one which has been proven on another spacecraft and which requires no modification for the mission under development

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UAH**Introduction**

- Command messages can originate from
 - Onboard computer
 - Uplink transponders
 - Hardline test interface
- Several standards exist for command message formats
- Commands consist of
 - Synchronization code
 - Spacecraft address bits
 - Command message bits
 - Error check bits

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Introduction

- Received command are validated prior to execution
- Validation – synchronization code, checking command message length, exactly matching spacecraft address, detecting errors in an error check polynomial code
- Once validated, decoder increments a counter to record number of executed commands
- Message bits pass to decoder for execution
- Data handling reads accept and reject counters – sends in downlink data

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Introduction

- Command decoder determines command output type and specific interface channel
- Two type of output
 - Discrete – fixed amplitude and fixed pulse duration; two types – high-level discrete command, and low-level discrete command
 - Serial – 3-signal interface consisting of shift clock, serial command data, and data enable used to indicate that interface is active
- Data handling combines telemetry from multiple sources and provides it for downlink or internal spacecraft use
- Most systems are time-division multiplexed – sequence inputs in predetermined order, then organize them in fixed output format

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Introduction

- Input signal sampling rate is determined by signal bandwidth
- Sample rate must be a minimum of two times the greatest frequency component contained in signal
- Data from all inputs is converted to digital form and formatted into a serial stream of continuous data for downlink
- Data handling may also supply telemetry to an onboard computer

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System Sizing Process

| Step | Procedure | Issues or Data Needed |
|--|--|--|
| 1. Identify which functions are to be performed by the CD&H system | Determine or estimate what on spacecraft must be controlled and what must be monitored to accomplish or support mission. Determine what tasks are to be performed on board | <p>Command Processing Is command processing required? If Yes, •What is command rate? •How many channels? •Is there a computer? •Are stored commands needed?</p> <p>Telemetry Processing Is telemetry processing required? If Yes, •How many channels? •What is housekeeping data rate? •What is payload data rate? •Is computer interface needed?</p> <p>Other Mission time clock needed? Computer watchdog needed? ACS functions needed?</p> |

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System Sizing Process

| Step | Procedure | Issues or Data Needed |
|--|--|---|
| 2. Identify requirements and constraints | Determine parameters, derived by aspects of overall spacecraft design, which impact C&DH system | Bus constraints Reliability Satellite lifetime Radiation environment Schedule Budget |
| 3. Determine complexity of C&H functions | Use Table 11-28 to estimate complexity of each function identified in step 1, applying constraints established in step 2 | Evaluate each function separately |

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System Sizing Process

| Step | Procedure | Issues or Data Needed |
|---|--|--|
| 4. Determine overall C&DH level of complexity | Collect functions into command and telemetry components and determine composite complexity of each | Are other functions such as mission time clock combined into command or telemetry? |
| 5. Estimate size, mass and power for each component | Apply results of step 4 to Table 11-29 for command and telemetry components | Combined systems (share housing, reduce interface cabling, may share power supply) |

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System Complexity Definitions

| Requirement or Constraint | Simple | Typical | Complex |
|-------------------------------|----------------|--------------------|-----------------|
| Processing commands: | | | |
| CMD rates | 50 cmd/s | 50 cmd/s | ≥ 50 cmd/s |
| Computer interface | None | Computer or stored | Yes |
| Stored commands | None | Cmds (not both) | Not needed |
| Number of channels | < 200 channels | 300-500 channels | > 500 channels |
| Processing of telemetry data: | | | |
| TLM rates | | | |
| Housekeeping data | 500-4 kbps | 4-64 kbps | 64-256 kbps |
| Payload data | None | 1-200 kbps | 10 kbps-10 Mbps |
| Computer interface | None | None | Yes |
| Number of channels | < 200 channels | 400-700 channels | >500 channels |

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System Complexity Definitions

| Requirement or Constraint | Simple | Typical | Complex |
|---------------------------|-------------|-------------------------------|---------------------------|
| Other: | | | |
| Mission time clock | None | Included | Included |
| Computer watchdog | None | Included if OBC | Included |
| ACS functions | None | None | Included |
| Bus constraints | Single unit | Single unit or multiple units | Integrated or distributed |
| Reliability-Class B parts | | | |
| Single string | 0.8233 | 0.7610 | 0.6983 |
| Redundant | 0.9875 | 0.9736 | 0.9496 |
| Reliability-Class S parts | | | |
| Single string | 0.9394 | 0.9083 | 0.8285 |
| Redundant | 0.9987 | 0.9964 | 0.9829 |

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UAH **System Complexity Definitions**

| Requirement or Constraint | Simple | Typical | Complex |
|------------------------------------|-----------|------------|------------|
| Radiation environment (total dose) | < 2 krads | 2-50 krads | 50K-1Mrads |
| Schedule (in months, after order) | | | |
| Class B parts | 6-12 | 6-12 | 9-18 |
| Class S parts | 9-18 | 9-24 | 9-24 |

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UAH **CD&H Size, Mass, and Power**

| | | Simple | Typical | Complex |
|-------------------------|------------------|-------------|-------------|---------------|
| Size (cm ³) | Command only | 1,500-3,000 | 2,000-4,000 | 5,000-6,000 |
| | Telemetry only | 1,500-3,000 | 4,000-6,000 | 9,000-12,000 |
| | Combined systems | 2,500-6,000 | 6,000-9,000 | 13,000-15,000 |
| Mass (kg) | Command only | 1.5-2.5 | 1.5-3.0 | 4.0-5.0 |
| | Telemetry only | 1.5-2.5 | 2.5-4.0 | 6.5-7.5 |
| | Combined systems | 2.75-5.5 | 4.5-6.5 | 9.5-10.5 |
| Power (nominal) (W) | Command only | 2 | 2 | 2 |
| | Telemetry only | 5-10 | 10-16 | 13-20 |
| | Combined systems | 7-12 | 13-18 | 15-25 |

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Basics

- Concerns
 - Interfaces to other equipment must be protected so that their faults do not propagate into command decoder
 - Non commands or signals appear on command outputs during application or removal of prime power
 - Command decoder designs basic philosophy – if integrity of command message is in doubt, command not issued
 - Safe operations require multiple commands configured in series forming a logical AND function
 - No commands that turn off command decoder
 - No commands to interrupt uplink source

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Final Note

- CD&H often one of last on spacecraft to be defined
- Tool used to configure, control, or program the payload and other spacecraft subsystems
- Equipment cannot be completely defined until requirements of other systems have been established
- Mission designer's main task to list command, telemetry, and other data need for each spacecraft system
- CD&H interfaces to nearly all spacecraft functions

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